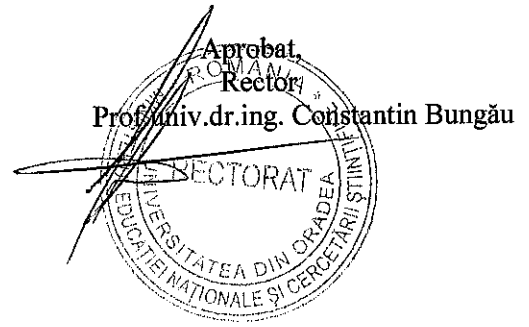UNIVERSITATEA din Oradea
Facultatea de Inginerie Managerială și Tehnologică
Departamentul de Inginerie Mecanică și Autovehicule

Aprobat,
Rector
Prof.univ.dr.ing. Constantin Bungău

BIBLIOGRAFIE:

1. Naser Eslam Pour, Path Planning of Unmanned Aerial Vehicles Using Particle Swarm Optimization and B-Spline Curves, 2009, M.Sc. Dissertation Thesis, Royal Military College of Canada
2. Madhav Devidas Patil, Heterogeneous Robot Swarm – Hardware. Design and Implementation, 2014, M.Sc. Dissertation Thesis, University of Bridgeport, Connecticut
3. Marcelo Oscar Sztainberg, Algorithms for Swarm Robotics, 2003, Ph.D. Thesis, State University of New York
4. Nicholas D Ernest, UAV Swarm Cooperative Control Based on a Genetic-Fuzzy Approach, 2012, M.Sc. Dissertation Thesis, University of Cincinnati.
5. Kimon P. Valavanis, George J. Vachtsevanos, editors, Handbook of Unmanned Aerial Vehicles, ISBN: 978-90-481-9707-1 (Online)
6. Jeffrey D. Barton, Fundamentals of Small Unmanned Aircraft Flight, Johns Hopkins APL Technical Digest, volume 31, number 2 (2012)
7. N. Correll, D. Rus, Architectures and Control of Networked Robotic Systems, In: Serge Kernbach (Ed.): Handbook of Collective Robotics, pp. 81-104, Pan Stanford, Singapore, 2013 .
8. Ester Martinez Martin, Editor, Swarm Robotics from Biology to Robotics, ISBN 978-953-307-075-9, 110 pages, Publisher: InTech, Chapters published March 01, 2010 under CC BY-NC-SA 3.0 license

Director contract conf.univ.dr.ing. Țarcă Ioan-Constantin